Hlookup(z, A, r, modifier) Takes a real input z, an array A of mixed real, complex, or string values, and a comparison criterion modifier. Hlookup matches $z$ in the first row of $\mathbf{A}$, subject to the conditions of modifier, and returns the result(s) in row $\mathbf{r}$ in the same columns as the matched elements.
z must be a scalar, unless you specify "range" as the comparison criterion, in which case it can be a 2 -element column vector.
$\operatorname{Lookup}(\mathbf{z}, \mathbf{A}, \mathbf{B}$, modifier) Takes a real input z, two arrays $\mathbf{A}$ and $\mathbf{B}$ of mixed real, complex, or string values, and a comparison criterion modifier. Lookup matches z in $\mathbf{A}$, subject to the conditions of modifier, and returns the value(s) in the same position(s) (that is, with the same row and column numbers) in matrix $\mathbf{B}$.
z must be a scalar, unless you specify "range" as the comparison criterion, in which case it can be a 2-element column vector.

Match(z, A, modifier) Takes a vector or matrix A of real, complex, or string values, a real input z to search for in $\mathbf{A}$, and a comparison criterion modifier, and returns a vector of indices for all matching elements in $\mathbf{A}$.
z must be a scalar, unless you specify "range" as the comparison criterion, in which case it can be a 2-element column vector.

VHlookup(z1, z2, A, modifier) Takes two values z1 and z2, an array $\mathbf{A}$ of real, complex, or string values, and a comparison criterion modifier. VHlookup matches z1 in the first column of $\mathbf{A}$ and z2 in the first row of $\mathbf{A}$, and returns the value at the intersection, subject to the conditions of modifier.

With VHlookup, either z1 or z2 can be a string, but not both. If either is a string, an exact match must be made in the corresponding row/column of $\mathbf{A}$.
vhlookup(z1, z2, A) Takes two values, z1 and z2, and an array $\mathbf{A}$ of real, complex, or string values. vhlookup matches z1 in the first column of $\mathbf{A}$ and z 2 in the first row of $\mathbf{A}$, and returns the value at the intersection. The accuracy of the match is controlled by TOL.

Vlookup(z, A, c, modifier) Takes a real input z, an array A of mixed real, complex, or string values, and a comparison criterion modifier. Vlookup matches $z$ in the first column of $\mathbf{A}$, subject to the conditions of modifier, and returns the result(s) in column $\mathbf{c}$ in the same rows as the matched elements.
z must be a scalar, unless you specify "range" as the comparison criterion, in which case it can be a 2-element column vector.

## Comparison Modifiers For Match And Lookup Functions

The following modifiers are supported by the Match and lookup functions provided as part of the Data Analysis Extension Pack:

| Comparison | Meaning |
| :--- | :--- |
| "near" | Returns the value closest to z. |
| "gt" | Matches everything greater than the value z. |
| "It" | Matches everything less than the value z. |


| "geq" | Matches everything greater than or equal to z. |
| :--- | :--- |
| "leq" | Matches everything less than or equal to z. |
| "not" | Matches everything not equal to z. |
| "range" | Matches everything in the specified range. z must be a two element vector containing <br> the upper and lower bounds of the range. |

$\operatorname{localmax}(\mathbf{M},[w])$ Takes a real $n \times 2$ matrix $\mathbf{M}$ and optional integer $w,=1$, and finds the local maxima in the second column of $M$. w (window width) is optional, and defaults to 1 ; for $w>1$, each point in the data must be greater than the surrounding $(2 w+1)$ points to be considered a local maximum to avoid false positives from noise. Function returns a 2 -column matrix of the $x$ and $y$ values for each maxima.
localmax $(\mathbf{x}, \mathbf{y}, \mathbf{M},[\mathbf{w}])$ The 3D version of this function takes vectors of x and y coordinates, a matrix of associated $z$ values, $\mathbf{M}$, and performs the same search for local maxima by nearest-neighbor comparison. M must have the same number of rows as $x$, and the same number of columns as $y$ has rows.
$\operatorname{localmin}(\mathbf{M},[w])$ Takes a real $n \times 2$ matrix $\mathbf{M}$ and optional integer $w,=1$, and finds the local minima in the second column of $\mathbf{M}$. w (window width) is optional, and defaults to 1 ; for $w>1$, each point in the data must be less than the surrounding $(2 w+1)$ points to be considered a local minimum. Function returns a 2 -column matrix of the $x$ and $y$ values for each minima.
localmin( $\mathbf{x}, \mathbf{y}, \mathbf{M},[\mathbf{w}])$ The 3D version of this function takes vectors of x and y coordinates, a matrix of associated $z$ values, $\mathbf{M}$, and performs the same search for local minima by nearest-neighbor comparison. $\mathbf{M}$ must have the same number of rows as x , and the same number of columns as y has rows.

